Differences Between EDCRASH and CRASH3

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ABSTRACT

Motor vehicle accident researchers have used the CRASH computer program for some time. Over the years, the code was upgraded until it reached its present and popular form, CRASH3, which runs on a mainframe computer or minicomputer with a sizeable memory capacity. A new version of the program, EDCRASH, has been developed which runs on personal computers using 128K of memory. This paper describes and compares this program with its mainframe counterpart. The program performed the same function as CRASH3, but was designed as a screen-oriented program utilizing the environment of the personal computer. Its design also allowed for file saving, graphics, routing of output, and interfacing with other accident reconstruction programs. For most accident types, the results for both programs were identical. However, for some types the results were different.

THE CRASH (CALSPAN RECONSTRUCTION of Accident Speeds on the Highway) computer program has been used as an effective tool for motor vehicle accident investigation for many years. Since its development in the early seventies [1-6], it has undergone many revisions and These changes have included refinements. debugging the code itself and modifications to improve its accuracy. It is doubtful that any computer program for use by accident investigators has received so much attention, undergone so thorough an evaluation, and provided so much useful data for those people who are concerned about highway accidents and their effect on our society.

*Numbers in brackets designate references at the end of the paper.

HISTORY AND PURPOSE OF CRASH

Since 1979, the National Highway Traffic Safety Administration (NHTSA) has implemented the CRASH program in a recent version, called CRASH3, for use by the National Accident Sampling System (NASS). Using a nationwide network of accident investigators, NASS has been developing a statistical database for the purpose of finding out what kind of accidents are the greatest threat to our society [7]. Automotive researchers have been able to use CRASH to provide collision dynamics for typical impact configurations in order to assess the effects upon occupant dynamics. This, in turn, aids vehicle designers who can use the results to build safer cars. Accident investigators use the program to help determine accident causation. Recently, the CRASH program has been used in the field of civil and criminal litigation, where it is an effective tool which can provide answers to technical accidentrelated questions.

PURPOSE OF THIS PAPER

This paper describes a recent version of the CRASH program called EDCRASH (Engineering Dynamics Corporation Reconstruction of Accident Speeds on the Highway). Its purpose is to compare EDCRASH with CRASH3, the version upon which it was based. First, similarties between the programs will be established. Then, because the major intent of this paper is to identify the differences between EDCRASH and CRASH3, those differences will be studied in the form of examples which illustrate the differences and their effect upon the results. Accident investigators familiar with CRASH3 can use this information to become familiar with EDCRASH. Others will become familiar with the general scope of either program.

OVERVIEW

The CRASH program provides a reconstruction of single- and two-vehicle accidents. The user supplies information gained from accident site and vehicle inspections. The program uses this information to determine the conditions at impact. The speed of the vehicle(s) at impact is produced only if scene data (impact/rest positions and path data) is supplied. Otherwise, the results are limited to speed change (a measure of impact severity). The program also produces intermediate results, such as separation velocities, energy absorbed by damage, and parameters associated with a trajectory simulation.

The results provide a consistent and well-validated methodology for the reconstruction of motor vehicle accidents. In addition, the program is a useful means of performing repeated analyses to test different accident scenerios (this is refered to as a "what if" analysis).

PROCEDURE

In order to provide a direct comparison between the programs, a version of CRASH3 dated December, 1981, was purchased from Mcauto (McDonnell Douglas Automation Co.) and compiled and executed on Boeing Computer Services' CDC-Cyber mainframe computer. EDCRASH, Version 2.0, dated July, 1984, provided the results on an IBM Personal Computer. Accessories included a 320K RAMdrive, IBM color/graphics adapter, and Epson MX-100 printer. Two different input data sets were supplied to each program and the results were examined. Various program options were exercised in order to evaluate conditions which led to different results. Similiarities and differences were then reported.

SIMILARITIES

EDCRASH and CRASH3 programs required the same input and yielded the same output. This was a major objective of program design, since researchers using both programs may be contributing to the same database.

Both programs were interactive. The user responded to questions (up to 50) requested at the terminal (either CRT or line printer). The input required quantitative data in three general categories. These were: (1) General Vehicle Data, (2) Accident Site Data, and (3) Vehicle Damage Data.

The General Vehicle Data defined vehicle dimensional and inertial properties and the relationship (mutual orientation) of the vehicles at impact. The Accident Site Data identified vehicle positions at impact, vehicle positions at rest, and how the vehicles moved from impact to rest (skidding, spinning,

braking, and tire/ground friction). The Damage Data supplied the measured location and profile of vehicle damage.

Not all questions required answers. Some had default answers and some only provided additional detail. A list of input questions can be found in the examples cited later in this paper. A description of each of the input data questions was beyond the scope of this paper. For such a description, the reader is referred to the literature [8,9].

The output session began with a display of error messages. These messages were categorized as either informative or fatal. In the latter case, execution was terminated and output was limited to damage-based results.

The form of the output was either complete or abbreviated. The complete form displayed the impact speed and speed change for both vehicles, followed by an echo of impact and separation conditions, trajectory simulation results, summary of damage data, and vehicle dimensional and inertial properties. The abbreviated results were limited to a summary of impact speeds and speed changes, and trajectory simulation results.

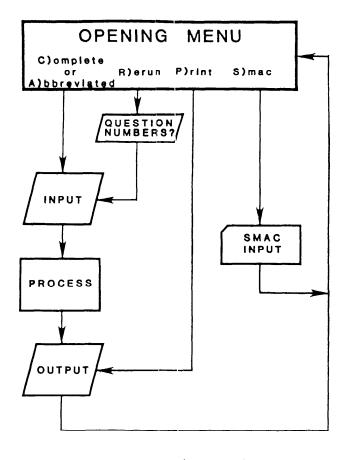


Figure 1 - Flow diagram for CRASH3

DUFFERENCES

The differences between EDCRASH and CRASH3 were found primarily in three areas: (1) User interactivity, (2) Calculations, and (3) Graphics.

User Interactivity

CRASH3 was coded in FORTRAN for use on remote input data terminals, usually connected to a mainframe computer. The terminal was a CRT or local line printer. In either case, the input questions and output results scrolled continuously, one line at a time.

EDCRASH was coded in compiled BASIC for use on the IBM PC or IBM compatible personal computer. As a result, the user interfaced with the program in a substantially different manner. This may be illustrated by inspection of flow diagrams for CRASH3 (figure 1) and EDCRASH (figure 2).

A CRASH3 session began at a menu which provided the user with a list of program options:

COMPLETE - The program ran through its entire cycle. All of the input questions and output results were presented in their most detailed formats.

ABBREVIATED - The program ran through its entire cycle. The input/output was presented in a concise format.

RERUN - The program was re-executed after changing the input for up to 12 questions (followed by processing and new results).

PRINT - Printed a Complete listing of the results.

SMAC - Generated an input data set for the SMAC (Simulation Model of Automobile Collisions [10]) program based on the CRASH3 results.

 ${\tt END}$ - Returned to the computer operating system.

The user initiated a CRASH3 run by selecting the type of run to be performed. If a complete run was requested, then all questions were displayed in a long and rather detailed (complete) form. If an abbreviated form was requested, the input questions were presented in a concise form. The user's memory could be refreshed by entering a ?, which caused the complete form of the question to be displayed. When the input session was concluded, the results were processed and the output was displayed. After each execution, the program returned to the menu, allowing the user to run an abbreviated program or rerun

with modified input, view the results, and follow up with input data changes and/or a complete form of the output listing. The user could then generate a SMAC input data set and exit the program. (The SMAC program can be used to test the CRASH results.)

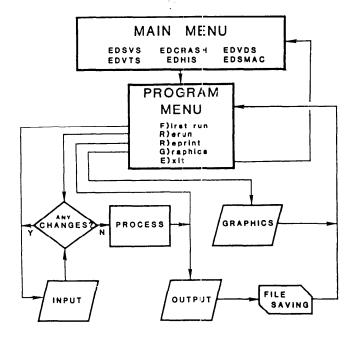


Figure 2 - Flow diagram for EDCRASH

EDCRASH was one of a series of six accident reconstruction programs, all of which were displayed on a Main Menu. Execution was initiated by selecting EDCRASH from the Main Menu. The session began with a display of the Program Menu, which provided the user with a list of options:

FIRST-RUN, INTERACTIVE SESSION - Began the question/answer session in the abbreviated format. The complete form of any question was displayed at the bottom of the screen, along with the required answer format and sample answer, if a ? was entered.

RERUN WITH INPUT FROM A PREVIOUS SESSION - Initiated the rerun option, which required the user to supply an input file (the previous file was the default file; otherwise, any previously-saved input file could be supplied). The session began by asking which section of input required review and/or changes.

OUTPUT FROM A PREVIOUS SESSION - Redisplayed the output, which required the user to supply an output file (the previous session was the default file; otherwise, any previously-saved file could be supplied). The session began by asking for the desired form of output (complete or abbreviated) and routing (screen or printer).

PICTORIAL DISPLAY OF ACCIDENT SITE - Created a pictorial representation of the accident site, which also required the user to supply an output file.

EXIT TO MAIN MENU - Returned to the Main Menu in order to execute another program or exit to the operating system.

The user initiated the analysis by selecting the type of run to be performed. However, since EDCRASH had a file-saving option, three additional options were available when initiating a session. By appropriately selecting (1) rerun with previous input, (2) reprint previous output, or (3) pictorial display of accident site, the user could rerun, reexecute, or review the results of previous sessions without re-entering the input data.

When a first-run was requested and the input session was complete, or if a rerun was requested, EDCRASH asked the user if a review of the input data, or "Any Changes?", was desired. If so, the user could scan each of the sections of data (General, Scene, Impact to rest, Tire/road, and Damage) and accept the data or change it prior to execution. Processing was initiated by a negative response to "Any Changes?". Differences in processing may be found in a later section of this paper.

At the completion of the output session, EDCRASH allowed the user to save the input and/or output files, and then returned to the Program Menu for another run.

At this point, the user could perform a new run, rerun, reprint, graph, or terminate execution. If an EDSMAC input file was desired, it was not necessary to create one, since an EDCRASH output file structure was identical to an EDSMAC input file structure.

Calculations

RICSAC data sets, used during the development of CRASH [5], were used to demonstrate the calculations. RICSAC8 was used to provide typical input and output and establish a valid basis for results. Then, RICSAC7 was used to demonstrate the effects due to some coding differences.

The RICSAC8 input data, shown in figure 3, described an impact between two Chevrolet Chevelles. Vehicle #1 struck vehicle #2 at the passenger-side door. The angle of impact was 90 degrees (perpendicular). Both vehicles responded to impact by spinning clockwise while coming to rest. In order to process the input, the CDC-Cyber required approximately 1 second; the IBM required 5.2 seconds.

Figure 3 - RICSAC8 input data set

The computation results for CRASH3 are shown in figure 4 and the results for EDCRASH are shown in figure 5. All the results were shown (i.e., the "Complete" form was selected) in order to illustrate all the differences in output.

Neither program generated any warning messages and the results were indentical. EDCRASH reported some additional information, including Energy Absorbed by Damage, Magnitude of Principal Force, and Moment Arm of Principal Force, in the SUMMARY OF DAMAGE DATA.

After the preliminary output was reviewed, a rerun was performed and a trajectory simulation was requested. The response time for the CDC-Cyber was 4.5 seconds. The processing time for the IBM was 375.4 seconds. For purposes of brevity, only the abbreviated results were displayed.

Inspection of the output results (CRASH3, figure 6; EDCRASH, figure 7) revealed a difference in IMPACT SPEEDS AND SPEED CHANGES. The difference was due to an increase in the integration time interval. While CRASH3 used an interval of 0.025 seconds, EDCRASH used

SUMBAR, OF CRASHS RESULTS

RIDSAC #8 CHEVELLE VS CHEVELLE

VEHICLE # 1

IMFACI SPEED MFH		SI	PEED CHAP	NGE	BASIS	
FWD	LAT	TOTAL	LONG.	LATERAL	OF RESULTS	
16.7		12.6	-6.9	18.5	SPINOUT TRAJECTORIES AND CONSERVATION OF LINEAR MOMENTUM	
•••••	-				SPINOUT TRAJECTORIES AND DAMAGE	
•••••		11.8	-8.3	8.3	DAMAGE DATA ONLY	

VEHICLE # 2

LMF ACT SFEED MF H		SI	EEU CHAF	4GE	DASIS OF	
F W.D.	LAT	TOTAL	LONG.	LA TEFAL	•	
25.7	. 0	12.0	10.0	-6.6	SPINOUT TRAJECTORIES AND CONSERVATION OF LINEAR MOMENTUM	
	•				SPINOUT TRAJECTORIES AND DAMAGE	
• • • • • •		11.2	7.9	-7, 9	DAMAGE DATA UNLY	

SCENE INFORMATION

	AEHICLE #	1	VEHICLE #	2
IMPACT A POSITION	- 10.90	FT.	.00	FT.
IMPACT / POSITION	3.20	FT.	1.90	FT.
IMPACT HEADING ANGLE	.00	DEG.	89.99	DEG.
REST # PUSITION	50	FT.	6.50	FT.
REST V-FOSITION	12.00	FT.	21.00	FT.
REST HEADING ANGLE	45.99	DEG.	140.98	DEG.
DIRECTION OF ROTATION	_w		CW	
AMOUNT OF RUTHTION	360		. 360	

			COLLISION	CONDITIONS		
VE	HICLE	• 1		VEH	ICLE	* 2
, ,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,				XC2M' /C2M' PSI2M PSI2M BFTA2	:	.0 FT. 1.9 FT. 90.0 DEGREES .0 DEGREES
			SEFARATION	CONDITIONS P		
(CS): (CS):		19.9 9.8 19.5 58.1	ET. DEG MEH	XCS2' YCS2' PS1S2 US2 VS2 PS1SD1	:	.Ø FT. 1.9 FT. 90.Ø DEG 15.7 MPH -6.6 MPH 54.5 DEG/SEC

Figure 4 - CRASH3 results with RICSAC8 input

```
IMFACT SPEED (TRAJECTOR) AND CONSERVATION OF LINEAR MOMENTUM)
FORWARD LATERAL
VEH*1 10.7 MFH .8 MFH
VEH*2 25.7 MFH .8 MFH
SPEED CHANGE (DAMAGE)
TOTAL LONG,
VEHBL 11.8 MFH ~8.3 MFH
VEHB2 11.2 MFH ~7.9 MFH
SFEED CHANGE (LINEAR MOMENTUM)
TOTAL LONG,
VEHBI 12.6 MFH -6.9 MFH !
VEHB2 12.8 MFH -10.8 MFH
                               LONG, LAT.
-6.9 MEH 10.5 MEH
-10.0 MEH -6.6 MEH
ENERGY DISSIPATED BY DAMAGE VEH#1 08479,3 FT-LB VEH#2 31220.8 FT-LB
                                        RELATIVE VELOCITY DATA
SPEED ALONG LINE THRU CGS (LINEAR MOMENTUM)
VEHMS 5.6 HPH
SPEED ORTHOG, TO CG LINE (LINEAR MOMENTUM)
VEHMS 2.6 HPH
VEHMS 2.5 HPH
CLOSING VELOCITY (LINEAR MOMENTUM)
19.7 HPH
SUMMARY OF DAMAGE DATA
                                                                 ( * INDICATES DEFAULT VALUE)
                     VEHICLE # 1
                                                                                    VEHICLE # 2
DIMENSIONS AND INERTIAL PROPERTIES
               = 54.7 INCHES
= 59.2 INCHES
= 61.8 INCHES
= 45564.2 LB SEC*-2 IN
= 11.592 LB SEC*-2/III
= 78.8 INCHES
= 114.6 INCHES
= 58.5 INCHES
                                                                                     = 54.7 INCHES
= 59.2 INCHES
= 61.8 INCHES
= 456-W4.7 LD-5EC++2/IN
= 78.8 INCHES
= 114.0 INCHES
= 30.5 INCHES
                                                                      B2
TR2
12
                                    ROLLING RESISTANCE
     VEHICLE # 1
                                                                                      VEHICLE . 2
```

Figure 4 (continued)

0.100 seconds, mainly to reduce processing time. This decision was supported by the fact that CRASH2 also used a 0.100 second interval. For most results, the effect of this change was less than 0.3 mph.

The RICSAC7 data, selected in order to demonstrate the effects of some minor coding errors and additional diagnostic error messages, is shown in figure 8. This data described an impact between a Chevrolet Chevelle (Vehicle #1) and a Volkswagen Rabbit (Vehicle #2). The Chevelle struck the Rabbit at the passenger-side door. The angle of impact was 120 degrees (slighlty more than perpendicular). The Rabbit responded by spinning clockwise and rolling a short distance before coming to rest. The Chevelle was redirected by the force of impact, but continued along an essentially straight course, without spinning, to its rest position.

ENGINEERING DYNAMICS CORPORATION Date 12-06-1984 fime 11:02:44 SAMPLE RUN RICSAC CASE 08 11/26/00

WARNING MESSAGES: NO MESSAGES

VEHICLE #

SF E MF	ED	SPEED CHANGE MFH		IGE:	BASIS OF
FWD :	LAT	TOTAL	LONG.	LATERAL	-: RESULTS
15.7	0.0	12.6	6.9	10.5	: SFINOUT TRAJECTORIES AND : CONSERVATION OF LINEAR : HOMENTUM
0.0	¥3. ±1	0.0	0.0	0.0	: SPINOUT TRAJECTORIES AND : DAMAGE
		11.8	-8.3	8.5	: DAMAGE DATA ONL!

VEHICLE # 2

IMFACT : SPEED CHANGE MFH : MPH			:	: DAS15 : OF						
FWD	:	LAT	:	TOTAL	: LI	DNG.	LA'	TERAL	-:	RESULTS
25.		۵. ت	:	12.0	-	10.0		-6.5	1	SFINOUT TRAJECTORIES AND CONSERVATION OF LINEAR MOMENTUM
e.e	:	4.4	:	2.2		0.0	:	0.0	1	SPINOUT TRAJECTORIES AND DAMAGE
			•	11.2	-	7.2	:	7.9	;	DAMAGE DATA DNL ?

SCENE INFORMATION

	VEHTCLE	•1	VEHICLE	#2
IMFECT x FOSITION	10.90	FT.	0.00	Fī.
IME . I CEOSITION	3.20	FT.	1.90	FI.
THE ALT DE ACTING ANGLE	ત. છત	υ € G.	89.97	DEG
REST 1 FOSITION	v.50	FT.	0.50	FT.
REST Y POSITION	12.00	FT.	21.60	FT.
REST NEWS (10) WHOLE	45.79	Ŀ€G.	140.78	DEC
DIRECTION OF ROTATION	Cw Sav		C#	
MODITATION OF FOLIATION	.00		-04	

IMPACT INFORMATION

	VEHICL	E #1	VEHICLE	#2
teractic restrict	18.7	FT.	11.4	FT.
THE WITTER STATE OF	5.2	ft.	1.7	rt.
IMPACT HEREITING HINGLE	8.0	DEG.	90.0	DEG.
IMPALT AMOUNTAE FORATION FAIR	0.0	DEGREEC	4.8	DEG/SEC
IMPALT SIZE SELF ANGLE	¥. V	DEG.	٧.٧	tÆG.
SECURENT OF A SECURITION	16.3	f1.	0.0	£1.
SEFARATION - FORITION	3.2		1.7	
JEF JUAN LIE ALLENG ANGLE		DEG.	70.0	DEG.
SEFARATION FORWARD VELOCITY	9.8	MEH	15.7	MENI
ATARATION LATERAL VELOCITY	141.5	METE	3.5	MEHI
SECALATION AND SAFE POTATION PATE	*8.2	DEG. SEC	54.5	DEG/SEC

1 17 F + +C	JF EED	CEMJECTORY	H115,	CONSERVATION	OF.	LINEAR	HOMENTON
F	UF-WAAF D	LATER	501				

TEH I	# 1	15. " MFH	g,a MPH			
-E11	• .	25.7 MEH	0.0 MEH			
	SF E	i to Committee of	DaMe(GE)			
		. 1	LONG.	LAT.	ANG.	
511		LL 9 MEN	B. J. MEH	8.3 MFH	-45.0 DEG.	
			-7.9 MFH	7,7 MFH	45.0 DEG.	
	SFF	ES CHANGE (LINEAR MOMENTUM)			
	J. C	TOTAL	L ONG.	LAT.	ANG.	
EH		12.6 MEH	6.9 MFH	10.5 MFH	-56.6 DEG.	
JEH I	• ?	LLLW MEN	Let. W MEH	6.6 MPH	33.4 DEG.	
ENEG	G+	DISSIFATED	BY DAMAGE: VEH #1	38479,3	FT-LB VEH #2	31220.9 FT-LB

RELATIVE VELUCIT: DATA

SFEED ALONG L	NE THRU CGS (LINEAR MOMENTUM)
	15.5 MEH
26 ec - ■ 2	S. O. MEN
SEED BOOKS	TO CG LINE (LINEAR MOMENTUM)
	vi .m++i
VE.4 ●2	25.5 MEN
7. 15.75d .F. W	I - LINEAR MOMENTUM
	17. THERE

Figure 5 - EDCRASH results with RICSAC8 input

VEHICLE #1 VEHICLE #2	SUM NUTE: '••'	MARY OF DAMAGE DATA indicates default valu	ie.
CRUSH DEPTH 2		VEHICLE #1	VEHICLE #2
CRUSH DEPTH 2	CLASS (SIZE) CATEGOR:	4	4
CRUSH DEPTH 2	WEIGHT	44.9.0 LBS.	4710 0 LES
CRUSH DEPTH 2	CDC	11FDEW1	#CRYENC
CRUSH DEPTH 2	DAMAGE WIDTH	73.0 IN.	84.5 IN
CRUSH DEPTH 4		2.7 IN.	6.2 IN.
CRUSH DEPTH 4		3.6 IN.	8.3 IN.
CRUSH DEPTH 5			9.2 IN.
COUNTY C		w.e IN.	5.9 IN.
DAMAGE MIDPOINT OFFSET		0.0 IN	4.4 IN.
DIMENSIONAL INERTIAL AND TIRE ROAD PROPERTIES		0.0 IN.	0.8 IN.
DIMENSIONAL INERTIAL AND TIRE ROAD PROPERTIES	DAMAGE MIDFOINI OFF SET	e.e in.	15.0 IN.
DIMENSIONAL INERTIAL AND TIRE ROAD PROPERTIES	DAMAGE ENERGY	38479.3 FTLB.	31220.9 FTLB.
DIMENSIONAL INERTIAL AND TIRE ROAD PROPERTIES	MAGNITUDE OF PRINCIPAL FORCE	477.6.9 LE.	54794.6 LB.
DIMENSIONAL. INERTIAL AND TIRE ROAD PROPERTIES VEHICLE #1 VEHICLE #2 CG TO FRONT AXLE CG TO FRAN CG	DIMECTION OF PRINCIPAL FORCE	-45.0 DEG.	45.0 DEG.
DIMENSIONAL. INERTIAL AND TIRE ROAD PROPERTIES VEHICLE #1 VEHICLE #2 CG TO FRONT AXLE CG TO FRAN CG	MUMENT ARM OF PRINCIPAL FORCE	70.0 IN.	19.2 IN.
CG TO FRONT AXLE CG TO FRONT AXLE CG TO FEAR CG TO FEA	DAMAGE CENTROID	1.7 IN.	7.8 IN.
MASS 1.6 LB-SEC**2-IN 456M87 LE-SEC**2-IN 80DY LENGTH FROM CG TO FROM 1 90.0 IN. 78.0 IN. 80DY LENGTH FROM CG TO REAR 114.0 IN. 114.0 IN. 90DY WIDTH 75.0 IN. 77.0 IN.	CG TO FRONT AXLE	VEHICLE #1	
MASS 16 LB-SECTO IN 12.2 LB-SECTO M 800W / LB-SECTO M 12.2 LB-SECTO M 98.8 IN 98.8 IN 114.8 IN 114.8 IN 114.8 IN 114.8 IN 17.8 IN 17	CG TO PEAR AXLE	53.7 10	54.7 IN.
HASS 16 LB-SEC 2-1 N 12.2 LB	TRACI WIDTH	AL B IN	59.2 IN.
BODY LENGTH FROM CG TO REAR 111.0 IN. 114.0 IN. 1100 MIDTH 77.0 IN. 77.0 IN. 77.0 IN.	AW MOMENT OF INEFTIA	4.3364. 3 LB SEC 23 to	61.8 IN.
ODY LENGTH FROM CG TO REAR 111.0 IN. 114.0 IN. 1007 WIDTH 77.0 IN. 77.0 IN. 77.0 IN.	1ASS	1 . 6 LB-SEC-2 IN	456MM. / LE-SEC 2 - I
### ##################################	BODY LENGTH FROM CG TO FRONT	28.8 IN.	12.2 LB-SEC-2/1
### ##################################	BODY LENGTH FROM CG TO REAR	111.0 IN.	114 . 10.
FOLLING RESISTANCE (LONT FRONT TIRE 0.01 0.01 LEFT FRONT TIRE 0.01 0.01 LONT FLAR TIRE 0.20 0.20 LEFT REAR TIRE 0.20 0.20 LEFT REAR TIRE 0.20 0.20	BODY WIDTH	The In.	77.0 In.
	FOL	LING RESISTANCE	
EFT FRONT TIPE	RIGHT FRONT TIRE	e1. #1	a ai
RIGHT FLAR TIME	EFT FRONT TIRE	41.411	
LEFT REAR TIRE 0.24 0.24 TIRE ROAD TRICTION 8.87 4.87	RIGHT FLAR TINE	4.20	
TINE POND TRICTION N.87	LEFT REAR TIRE	v. 20	
	TIRE POND PRICTION	W- 87	

Figure 5 (continued)

```
MICSHC #8 CHEVELLE VS (HEVELLE

IMPACT SPEED (TRAJECTORY AND CONSERVATION OF LINEAR MOMENTUM)
FORMARD
VEHRE 19,5 MEH A MIN
VEHRE 21,8 MEH A MIN
VEHRE 21,8 MEH A MEH

SFEED CHANGE (DAMAGE)
1016L LONG, LAT, ANG,
VEHRE 11,8 MEH B-7 MEH 8,7 MEH 45,8 DEG,
VEHRE 11,8 MEH 7,7 MEH 7,7 MEH 45,8 DEG,
VEHRE 11,8 MEH 1,7 MEH 7,7 MEH 45,8 DEG,
VEHRE 18,1 MEH 1,7 MEH 1,7 MEH 45,8 DEG,
VEHRE 18,1 MEH 1,5 MEH 8,5 MEH 45,8 DEG,
VEHRE 17,2 MEH 8,1 MEH 1,5 MEH 8,5 MEH 2,8 DEG,
VEHRE 17,2 MEH 8,1 MEH 1,5 MEH 8,5 MEH 2,8 DEG,
VEHRE 17,2 MEH 8,1 MEH 1,5 MEH 8,5 MEH 2,8 DEG,
VEHRE 17,2 MEH 8,1 MEH 1,5 MEH 8,5 MEH 2,8 DEG,
VEHRE 19,2 MEH 8,1 MEH 1,5 MEH 8,5 MEH 2,8 DEG,
VEHRE 19,2 MEH 8,5 MEH MOMENTUM)
VEHRE 2,5 MEH 19,2 MEH VEHRE 2,5 MEH 19,2 MEH
VEHRE 2,5 MEH 19,2 MEH 19
```

TEAJECTOR: SIMULATION RESULTS

**** VE	HILLE	# 2 DID NOT	CONVERGE ****		
NEUNS CL) ±	5	NRUNS (25 =	5
E1(1)		. 487	E2(1)	=	. 470
E1(2)	-	. 000	E2(2)		.000
E1(3)	-	. 257	E2 (5)	-	. 155
E1(4)	=	. 000	E2(4)		.000
E1(5)	-	. 666	E2 (5)	3	.000
OMINI		. 347	CMING		. 231

**** VEHICLE # 1 DID NOT CONVERGE ****

Figure 6 - CRASH3 results for RICSAC8 with a trajectory simulation

```
SUMMARY OF EDERASH RESULTS
ENGINEERING DYNAMICS CORPORATION Date 12:06-1984 Time 11:13:14 SAMPLE RUN RICSAC CASE #8 11/26/80
   WARNING MESSAGES: NO MESSAGES
    IMPALT SPEED (TRAJECTOR) AND CONSERVATION OF LINEAR MOMENTUM)
FURNARD LATERAL
VIJ. 81 19-1 HPH 0.0 HPH
VIJ. 82 22-1 HPH 0.0 HPH
                     SPEED CHANGE (DAMAGE)
     10% AL 11.8 MEH
VIH #1 11.2 MEH
VIH #2 11.2 MEH
                                                                                                                L CING
                                                                                                  8.3 MEH
-7.9 MEH
                                                                                                                                                                                                                                 45.0 DEG.
45.0 DEG.
                SPEED CHANGE (LINEAR MOMENTUM)
   ENERGY DISSIPATED BY DAMAGE: VEH #1 38479.3 FT-LB VEH #2 31220.9 FT-LB
                                                                                                                           RELATIVE VELOCITY DATA
     STREED HEUNIG EINE THRU EGS KEINEAR MOMENTUM:
VEH MI 12.0 MEH
VEH ME 2.6 MEH
     SPEED OFFINIOS TO CG LINE (LINEAR HOMENTUM)
VEH #1 21.7 MPH
VEH #2 21.7 MPH
   CLOSING VERWEITE FLINEAR MOMENTUMP
                                                                                                                           TRAJECTOR: SIMULATION RESULTS
     *****EHICLE # 1 DID NOT CONVERGE ****
    PROMITED OF BOATS CHARMMORE STORMS FOUNT TOWN A CERTAIN CONTROL OF STORMS FOR A CONTROL OF STORMS FOR
```

Figure 7 - EDCRASH results for RICSAC8 with a trajectory simulation

In order to process the input for RICSAC7, the CDC-Cyber computer required approximately 1 second; the IBM PC required 3.9 seconds.

The computation results for CRASH3 are shown in figure 9 and the results for EDCRASH are shown in figure 10. The complete form of cutput is shown in order to illustrate all the differences.

CRASH3 did not display any warning messages. EDCRASH generated two warning messages, both informative (i.e., non-fatal). The first message (refer to figure 10) told the user of an inconsistency in the damage data: Since the damage data (user-measured and table-supplied) for each vehicle was totally independent, but the vehicles' response had to obey Newton's three laws of motion, this was a check of consistency for vehicle damage data for both vehicles. The error message generated by EDCRASH indicated the force required to cause the observed (measured) damage for each vehicle was very dissimilar (the difference was

GENERAL INFUT DATA

Figure 8 - RICSAC7 input data set [5]

greater than 100%). The source of the error was either (1) incorrect interpretation and/or measurement of damage, or (2) inappropriate stiffness data used by the program. The cause of the error should be identified, either by close inspection of the damage measurements or the vehicle crush stiffness parameter(s).

The second warning message issued by EDCRASH informed the user that an adjustment of vehicle separation velocities was performed in order to satisfy an assumption common to both programs: The regions of each vehicle which contact one another during the collision must reach a common velocity just prior to separation. The separation velocity for each vehicle was determined independently during the post-impact phase calculations. If the input data (impact/rest/end of rotation/point on curve positions, tire-ground friction, and wheel lock-ups) were perfect - and if the 3degree of freedom model were exact - then the velocity (speed and direction) of the regions of contact would be exactly the same for both

SUMMARY OF CRASH3 RESULTS

RICSAC #7 CHEVELLE VS RABBIT

VEHICLE # 1

	ACT EED PH	SI	SPEED CHANGE MFH		BASIS
FWD	LAT	TOTAL	LONG.	LATERAL	OF RESULTS
26.2		15.0	13.5		SPINDUT TRAJECTORIES AND CONSERVATION OF LINEAR MOMENTUM
					SPINOUT TRAJECTORIES AND DAMAGE
	,	19.7	-17.1	9.9	DAMAGE DATA ONLY

VEHICLE # 2

	IIII. SFE MF	ED C	SI	PEED CHAI MFN	NGE .	teasts of
:	ь	Lu1	f@fAL	LUNG.	LATERAL	•
34	1.7	. 4	52. 1	27.0	-18.4	SPINOUT TRAJECTORIES AND CONSERVATION OF LINEAR MOMENIUM
						SPINOUT TRAJECTORIES AND COMMAGE
			43.0	-37.2	-21.5	DAMAGE DATA ONLY

SCENE	INFORMATION
	SERTO

	VENTURE #	•	venices •	
THEHCT X FOSTITON	. 00	FI.	10.70	ET.
(MEACT + FOSITION	. 00	FT.	3, 45	FT.
IMPACT HEADING ANGLE	- 644	DEG.	119.99	DEG.
REST + FOSITION	84.50	FT.	22.90	FT.
HEST 1-FUSITION	18.20	FT.	41.40	FT.
REST HEADING ANGLE	16.50	DEG.	261.97	DEG.
END-OF FOTATION K-FOSITION	. 00	FT.	22.00	FT.
END-OF-ROTATIONFOSITION	, 40	FT.	30.00	FT.
END OF ROTATION HEADING ANGLE	. 00	DEG.	249.97	DEG.
DIRECTION OF ROTATION	CW		CW	
AMOUNT OF BOTATION	760		. 766	

VEHICLE # 2

COLLISION CONDITIONS

VE	HILLE	• 1		VEHI	CLE	a 2	
• 5 1 • · ·	-	, a	rr.	×020°	_	10.7	FT.
70.10F	=	. છ	FI.	ACSM.	13	3.4	FT.
15110	-	. 📢	DEGREES	FS120		120.0	DEGREES
FSLIDE		. 0	DEG/SEC	FS12DW	a	. 0	DEG/SEC
HE LMI	•	ان .	DEGPEES	DETAR	•	. 0	DEGREES
			3EFAFA110	ON CONDITIONS			
4CS1"		. •	FT.	4CS2*	_	10.7	FT.
*C51	-	. 11	FT.	YCS2"	-	3.4	FT.
F 24.54		. 4	DEG	PSIS2	•	120.0	D€G
USI	-	1	MEH	US2	=	8.0	MPH
251	-	0.5	196-14	/S.	-	18.4	HEH
151301		. 10	DEG: SEC	ESISD2	-	146.1	DEG/SEC

Figure 9 - CRASH3 results with RICSAC7 input

```
IMPACT SPEED (TRAJECTORY AND CONSERVATION OF LINEAR HOMENTUM:
FORMARD LATERAL
11 26.2 MPH , 0 MPH
12 34.9 MPH , 0 MPH
        SPEED CHANGE (DAMAGE)
        SPEED CHANGE (LINEAR MOMENTUM)
TOTAL LONG.
                               LONG.
-13.5 MPH
-27.0 MPH
                                                       LAT.
6.5 MFH
-18.4 MFH
 ENERGY DISSIPATED BY DAMAGE VEH#1 23188.8 FT-LB VEH#2 196486.9 FT-LB
                                      RELATIVE VELOC: TY DATA
SPEED ALONG LINE THRU CGS (LINEAR MOMENTUM)
VEH01 24.9 MPH
VEH02 7.3 MPH
SPEED ORTHOG, TO CG LINE (LINEAR MOMENTUM)
VEH02 -34.2 MPH
CLOSING VELOCITY (LINEAR MOMENTUM)
32.2 MPH
32.2 MPH
  SUMMARY OF DAMAGE DATA
                                                               . INDICHTES DEFAULT VALUE
                    VEHICLE # 1
                                                                         -----CATEGORY
DIMENSIONS AND INERTIAL PROFERIES

    54.7 INCHES
    77.2 INCHES
    61.6 INCHES
    5882.2 US SUC+, INCHES
    61.6 INCHES
    61.6 INCHES
    61.6 INCHES
    61.6 INCHES
    61.6 INCHES
    61.6 INCHES

                                                                                      e er i de
La stronge
                              COUNTY OF THE STREET
                                                                              VEHICLE • 2
NU ------
```

Figure 9 (continued)

This velocity was computed at the damage centroid and compared for both vehicles. If the velocity difference was less than 10 percent, the average velocity was used as the common velocity. If the difference was more, then the separation velocity for one vehicle was decreased and the other was increased by 10 percent. If the resulting difference, after the adjustment, was less than 10 percent, then the observed warning message (see figure 10) was issued. If the resulting difference were still greater than 10 percent, then a fatal error message would have been issued and execution halted. The purpose of such a check was to disallow an analysis which was not within the scope of the analysis, such as a sideswipe. Both programs performed the above check. However, CRASH3 only reported the condition after two adjustments and did not

ENGINEERING DYNAMICS CORFORATION Date 10-08-1984 Time 12:32:36 RIESAC W7 CHEVELLE V5 RABBIT

WARNING MESSAGES:

Demands based estimates for Magnitude of Principal Force grossly violate Nawton's third law of motion. Review the output to determine required corrections to Damade Data and adjust as necessary. The Magnitudes of Principal Force for Vehicles 1 and 2 should be approximately equal.

COMMON VELOCITY WARNING -- An adjustment of vehicle separation conditions was performed in order to be consistent with the common velocity assumption. The adjustment does not exceed 10 percent.

			MPH		: OF : RESULTS	
FWD :	LAT :	TOTAL :	LONG.	LATERAL		
25.9	4.0	14.8	-13.3	5.5	: SPINGUT TRAJECTORIES : CONSERVATION OF LINEA : MOMENTUM	
0.0	0.0	0.0	0.0		: SPINOUT TRAJECTORIES : DAMAGE	AND

IMEA	cr :				:	
SEE	ED :	SF	EED CHAN	CE	;	BASIS
HE			MPH		:	OF
					٠:	FESULTS
	LAT :	foral :	LONG. :	LATERAL	:	
					:	SPINOUT TRAJECTORIES AND
74.7	0.0	32.1 3	-26.7 :	17.9	:	CONSERVATION OF LINEAR
	:	:	:		;	MORENTUM
•	•					SPINOUT TRAJECTORIES AND
10° 10°	V. V.	0.0	9.0	0.0	:	DAMAGE
			,		•	DHITHUE
			37.2		•	DAMAGE DATA ONLY

	VEHICLE	. •1	VEHICLE	#2
MEALT & FOSTTION	0.00		10.70	
MEACT + FOSITION		Fľ.	3.45	
MEACT HEADING ANGLE	0.00	DEG.	119.99	DEG.
Est x-FOSITION	84.50		22.90	
EST + FOSITION	18.20		41.40	
EST HEADING ANGLE	16.50	DEG.	261.97	DEG.
NO DE SOINTION & POSITION	0.00	FT.	22.00	
NO UF RUINTION + FOSITION	11.00		30.00	
ND OF FOTATION HEADING ANGLE	4.00		249.97	DEG.
IRECTION OF ROTATION	CW		CW	
HOUNT OF RUTATION	360		360	
IMPAC	CT INFORMATI	0N		
	VEHICLE	•1	VEHICLE	•2
MEACT X FOSITION		FT.	10.7	
MEACT + ESTITION	r. r.		5.5	
MFACT HEADING ANGLE	0.0		120.0	
MEACT ANGULAR ROTATION RATE		DEG/SEC	0.0 0.0	DEG/SE
MEACT SIDESLIP ANGLE	0.0	DEG.	0.0	DEG.
SEFARATION & FOSITION	0.0	FT.	10.7	
SEPARATION 1-POSITION	4.0	F1.	3.5	FT.
SEFARATION HEADING ANGLE	0.0	DEG.	120.0	
SEPARATION FORWARD VELOCITY	12.7		8.0	
	6.5		-17.9	
SEFTMATION LATERAL VELOCITY SEPARATION ANGULAR ROTATION RATE		DEG/SEC		DEG/SE

	FORWARD	LATERAL			
ÆH #1	.5.9 MEH	U.U MEH			
VEH #2	34, 1 MEH	ø.ø MPH			
SFI	EED CHANGE (DA	MAGE)			
	TOTAL	LONG.	LAT.	ANG.	
VEH #1	19.7 MFH	-17.1 MFH	9.9 MFH	-30.0 DEG.	
VEH #2	43.0 MPH	-37,2 MEH	-21.5 MFH	co.ø DEG.	
SFI	EED CHANGE (LI	NEAR MOMENTUM			
	TOTAL	LONG.	LAT.	ANG.	
VEH #1	14.8 MFH	-13.3 MPH	6.5 MFH	-26.1 DEG.	
VEH #2	*2.1 MEH	26.7 MPH	-17.9 MFH	33.9 DEG.	
ENERGY	DISSIFATED DE	DAMAGE: VEH	#1 23188.8	FT-LB VEH #2	196487.1 FT-LB

Figure 10 - EDCRASH results with RICSAC7 input

RELATIVE VELOCITY DATA

SPEED ALONG	LINE THRU COS	(LINEAR	MOMENTUM)
VEH #1	24.7 MFH		
VEH #2	7.3 MPH		

SPEED ORTHOG. TO CG LINE (LINEAR MOMENTUM VEH #1 -8.0 MFH VEH #2 -33.9 MFH

CLOSING VELOCITY (LINEAR MOMENTUM)

SUMMARY OF DAMAGE DATA NOTE: '**' indicates default value

	VEHICLE #1	VEHICLE #2
CLASS (SIZE) CATEGORY	4	?
WEIGHT	3700.0 LBS.	1700.0 LBS.
CDC	11FDEW1	Ø2RDEW4
DAMAGE WIDTH	66.11 IN.	108.5 IN.
CRUSH DEPTH 1	Ø.15 IN.	0.0 IN.
CRUSH DEPTH 2	1.; IN.	11.0 IN.
CRUSH DEPTH 3	2.6 IN.	17.8 IN.
CRUSH DEPTH 4	3.8 IN.	21.0 IN.
CRUSH DEPTH 5	5.0 IN.	21.3 IN.
CRUSH DEFTH 6	6. 3 IN.	7.3 IN.
DAMAGE MIDPOINT OFFSET	4.9 IN.	-8.5 IN.
DAMAGE ENERGY	25188.3 Ft. LB.	196487.1 FT. LB.
MAGNITUDE OF PRINCIPAL FORCE	34913.4 LB.	246470.7 LB.
DIRECTION OF PRINCIPAL FORCE	30.∂ DEG.	10.0 DEG.
MOMENT ARM OF PRINCIPAL FORCE	61.3 IN.	22.2 IN.
DAMAGE CENTROID	15.5 IN.	-1.3 IN.

DIMENSIONAL. INERTIAL AND TIRE ROAD PROPERTIES

	VEHICLE #1	VEHICLE #2
CG TO FRONT AXLE	54.7 IN.	46.3 IN.
CG TO REAR AXLE	59.2 IN.	50.1 IN.
TRACE WIDTH	61.8 IN.	54.6 IN.
YAW MOMENT OF INERTIA	33822.2 LB-SEC 2-1N	12983.2 LB-SEC 2-IN
MASS	9.6 LB-SEC 12/1N	4.4 LB-SEC^2/IN
BODY LENGTH FROM CG TO FRONT	78.8 IN.	83.3 IN.
BODY LENGTH FROM CG TO FEAR	-114.# IN.	-91.6 IN.
BODY WIDTH	77.0 IN.	67.2 IN.
	ROLLING RESISTANCE	
RIGHT FRONT TIRE	8.81	0.01
LEFT FRONT TIRE	0.01	0.01
RIGHT REAR TIRE	0.20	1.00
LEFT REAR TIRE	Ø. 2#	0.20
TIRE/ROAD FRICTION	.e	W.87

Figure 10 (continued)

issue a fatal error in the event the common velocity assumption was not satisfied.

The next difference between the programs was found in the IMPACT SPEEDS AND SPEED CHANGES. This difference depended on the CRASH3 code which was used and only occurred if the post-impact path for vehicle #2 had an end-of-rotation position. It was due to an error in subroutine START2, wherein the separation coordinates for vehicle #2 were incorrectly assigned the end-of-rotation coordinates rather than the impact coordinates:

5 XCSP=XC12 YCSP=YC12

> should be

5 XCSP≃XC:2Ø YCSP≃YC:2Ø

The only other difference was found in the SUMMARY OF DAMAGE DATA section of output, described earlier. Reporting the Magnitude of Principal Force was useful when an error message indicated there was a gross difference in vehicle damage data (figure 10).

After the preliminary output was reviewed, a rerun was performed and a trajectory simulation was requested. The response time for a CDC-Cyber computer was 4.5 seconds. The processing time for the IBM PC was 239.3 seconds. (Only the abbreviated results are displayed.)

SUMMARY OF CRASHS RESULTS

Figure 11 - CRASH3 results for RICSAC7 with a trajectory simulation

Inspection of the output results (CRASH3, figure 11; EDCRASH, figure 12) again revealed a difference in IMPACT SPEEDS AND SPEED CHANGES. The difference was due to two different sources: (1) the end-of-rotation error, and (2) increasing the integration time interval from 0.025 to 0.100 seconds. Each of these differences has been described earlier. The effect of increasing the integration time step has been shown to be minor (refer to figures 6 The major cause of the difference was the end-or-rotation error, which provided the trajectory simulation a substantially different set of initial velocities (especially angular velocity; see figures 9 and 10, Separation Conditions).

```
ENGINEERING DYNAMICS CORPORATION Date 12:08-1984 Time 12:50:02 RICSAC #7 CHEVELLE VS RABBIT
 WARNING MESSAGES:
Damage-based estimates for Magnitude of Principal Force grossly violate 
Newton's third law of motion. Review the output to determine required 
corrections to Damage Data and adjust as necessary. 
The Magnitudes of Principal Force for Vehicles 1 and 2 should be 
approximately equal.
COMMON VELOCITY WARNING -- An adjustment of vehicle separation conditions was performed in order to be consistert with the common velocity assumption. The adjustment does not exceed 10 percent.
        IMPACT SPEED (TRAJECTORY AND CONSERVATION OF LINEAR MOMENTUM)
FORWARD LATERAL
41 29.5 MPH 0.0 MPH
42 53.7 MPH 0.0 MPH
        SPEED CHANGE (DAMAGE)
TOTAL LONG.
VEH #1 19.7 MPH
VEH #2 43.2 MPH
        SPEED CHANGE (LINEAR MOMENTUM:
TOTAL
VEH #1 19.9 MFH
VEH #2 43.3 MPH
                                        LONG.
-16.2 MPH
39.4 MPH
ENERGY DISSIPATED BY DAMAGE: VEH #1 23188.8 FT LB VEH #2 196487.1 FT LB
                                                      RELATIVE VELOCITY DATA
SPEED ALONG LINE THRU CGS (LINEAR MOMENTUM)
SPEED ORTHOG. TO CG LINE (LINEAR MOMENTUM)
VEH #1 -9.0 MPH
VEH #2 -52.5 MPH
CLOSING VELOCITY (LINEAR MOMENTUM)
                                                      TRAJECTORY SIMULATION RESULTS
****VEHICLE # 1 DID NOT CONVERGE ****
**** VEHICLE # 2 CONVERGED DF ****
                                                                        VEHICLE #1
                                                                                                                 MENTICLE OF
NUMBER OF RUNS (MAXIMUM OF 5)
REST POSITION X = EFFOR ( = 14)
END OF ACTATION X = EFFOR ( = 15)
REST POSITION HEADING EFFOR ( = 15)
END-OF-ROTATION HEADING EFFOR ( = 15)
POINT-DN-CURVE X = Y EFFOR ( = 15)
TOTAL WEIGHTED ERROR SUM
                                                                            8.265
8.000
1.078
8.000
```

SUMMARY OF EDERASH RESULTS

Figure 12 - EDCRASH results for RICSAC7 with a trajectory simulation

For purposes of illustration, another rerun was performed and the trajectory simulation option was turned off. Then, the post-impact trajectory of vehicle #1 was changed so that it was curved. Both programs modelled the curved path by assuming the path was defined by a circle. The position of vehicle #1 at impact and rest defined two points on the circle, and required a third point to be supplied by the user. This point allowed the radius (which was assumed to be constant) of the path and the path length to be calculated. In addition, it allowed the separation (i.e., post-impact) angle to be based on the curved path, rather than the straight line between impact and rest positions. This feature was extremely important, since the separation angle had a great effect on separation velocity. In order to use this feature, a point on the curved path was entered:

Point on curve = 40,4

SUMMARY OF CRASHE RESULTS

RICSAC #7 CHEVELLE VS RAPBIT

SUMMARY OF RESULTS

RELATIVE VELOCITY DATA

SPEED ALONG LINE THRU CGS (LINEAR MOMENTUM)
VEHNE 25.8 H191
VEHNE 3.7 MH91
SPEED ORTHOG TO CG LINE (LINEAR MOMENTUM)
VEHNE -8.1 HP1
VEHNE 2.4.2 HP1
CLOSING VELOCITY (LINEAR MOMENTUM)
32.7 HF H

SCENE INFORMATION

	VENICLE # 1		VEHICLE # 2	
(MPACT + FOSTITON		FT.	10.70	
IMPACT : FOSTITUM IMPACT MEASIMO AMOLE		DEC.	3.45 119.79	
REST C FOSITION	84.79		22.7A	
REST / FOSITION REST HEADING ANGLE	18.20 16.50		261.97	
END-OF POTATION T-POSITION		FT.	22.00	
END OF FORATION A FOSTITION END OF FOTATION HEADING ANGLE		rec.	30.49 249.97	
FOINT ON CURVE & POSITION FOINT ON-CURVE Y-FOSITION	46.60 4.66			
DINE. TION OF HOTHION			, w	
MICCINI OF RUINTION	100			

Figure 13 - CRASH3 results with point on curve

These results (CRASH3, figure 13; EDCRASH, figure 14) have been limited to the abbreviated listing plus the echo of scene data, which displays the user-entered point on curve.

Inspection of the results again revealed a difference in IMPACT SPEEDS AND SPEED CHANGES, due only to the end-of-rotation error.

In order to investigate another feature related to curved post-impact trajectories, the point on curve was changed:

Point on curve $\approx 40,8.5$

The results (CRASH3, figure 15; EDCRASH, figure 16) revealed the IMPACT SPEEDS AND SPEED CHANGES were the same as those obtained without a point on curve. This intentional result was caused by the selection of a point which was on the straight line between impact and rest positions. EDCRASH issued an informative message indicating this was the case. Note the echo of scene data did not include the user-entered point on curve. This circumstance would not lead to erroneous results.

SUMMARY OF EDCHASH RESULTS

ENGINEERING DYNAMICS CORPORATION Date 12-08-1984 Time 12:55:23
RIGSAC #7 CHEVELLE MS RABBIT

WARNING MESSAGES

Damage-based estimates for Magnitude of Principal Force grossly violate Newton's third law of motion. Review the output to determine required corrections to Damage Data and adjust as increasery. The Magnitudes of Principal Force for Vehicles 1 and 2 should be approximately aqual.

COMMON VELOCITY WARNING —— An adjustment of vehicle separation conditions was performed in order to be consistent with the common velocity assumption. The adjustment does not exceed 10 percent.

| IMPACT SPEED (TRAJECTORY AND CONSERVATION OF LINEAR MOMENTUM)
FORWARD	LATERAL		
VEH	11	20.8 MPH	8.8 MPH
VEH	12	34.7 MPH	8.8 MPH
SPEED CHANGE (DANAGE)			
VEH	11	19.7 MPH	-17.1 MPH
VEH	12	12.8 MPH	-37.2 MPH
SPEED CHANGE (LINEAR MOMENTUM)			
TOTAL	LONG.	LA'.	
VEH	11	14.8 MPH	-15.3 MPH
VEH	13	14.8 MPH	-15.3 MPH
VEH	14.8 MPH	-12.7 MPH	-17.9 MPH

RELATIVE VELOCITY DATA

SPEED ALONG LINE THRU COS (LINEAR MOMENTUM)
VEH *1 24.7 MPH
VEH *2 7.3 MPH

SPEED ORTHOG. TO CG LINE (LINEAR MOMENTUM)
VEH *1 8.8 MPH
VEH *2 -33.7 MPH

CLOSING VELOCITY (LINEAR MOMENTUM)
22.8 MPH
22.8 MPH

SCENE INFORMATION

	VEHICLE	• 1	NEHIC'LE	•2
IMPACT X-POSITION	0.00	FT.	10.70	FT.
IMPACT Y POSITION	0.00	FT.	3.45	Ft.
IMPACT HEADING ANGLE	0.00	D€G.	119.99	DEG.
REST X-FOSITION	84.50	FT.	22.90	FT.
REST Y-FOSITION	18 . 4		41.40	FT.
REST HEADING ANGLE	10.50		261.97	
END OF -ROTATION X FOSTITON	0.00	٠.	22.00	FT.
END OF ROTATION Y-FOSITION	0.00	FT.	30.00	FT.
END-OF-ROTATION HEADING ANGLE	10.110		249.97	DEG.
POINT ON-CURVE & POSITION	40.10	F1.		
POINT ON CURVE Y-POSITION	4.110	FT.		
DIRECTION OF POTATION	CW		CW	
AMOUNT OF ROTATION	3.741		Jor	

Figure 14 - EDCRASH results with point on curve

Another condition was found which could cause misleading results, however. In order to illustrate this potential for error, the point on curve was again changed:

Point on curve = 40.85

The results (CRASH3, figure 17; EDCRASH, figure 18) revealed a significant difference for IMPACT SPEEDS AND SPEED CHANGES. The difference was caused by entering an errant point on curve (i.e., one which was too far away from the impact and rest positions to lie within the smallest possible circle drawn through the points which define the impact and rest positions). This was also the cause of the common velocity warning message issued by CRASH3 (figure 17).

RICSAC #7 CHEVELLE VS RABBIT

SUMMARY OF RESULTS

IM	PACT SPEED	(TRAJECTORY AND	CONSERVATIO	N OF LINEAR MO	MENTUM)
		. W MPH			
VEH#2	34.9 MEH	. Ø MFH			
SF	EED CHANGE	(DAMAGE)			
	TOTAL	LONG.	LAT.	ANG.	
VEH#1	19.7 MFH	-17.1 MPH	9.9 MPH	-30.0 DEG.	
VEH#2	43.ø MPH	-37.2 MEH	21.5 MPH	Sø.ø DEG.	
SP	EED CHANGE	(LINEAR MOMENTA)M)		
	TOTAL	LONG.	LAT.	ANG.	
VEH#1	15.8 MFH	-13.5 MPH	6.5 MFH	-25.0 DEG.	
	7 7 MEU	27. Ø MEH	TO A MON	A A DEG	

ENERGY DISSIFATED BY DAMAGE VEH#1 23188.8 FT-LB VEH#2 196486.9 FT-LB

RELATIVE VELOCITY DATA

SPEED ALONG LINE THRU CGS (LINEAR MOMENTUM)
VEH#1 24.9 MPH
VEH#2 7.3 MPH
SPEED UPTHOG. TO CG LINE (LINEAR MOMENTUM)
VEHICL BUOMEN
VEH#2 -34.2 MPH
CLOSING VELOCITY (LINEAR MOMENTUM)
3.2. 2. MEH

SCENE INFORMATION

	VEHICLE # 1 %		VEHICLE .	VEHICLE • 2	
IMFACT x-FOSITION	. 40	FT.	10.70	FT.	
IMPACT V-POSITION	. 30	FT.	5, 45	FT.	
IMPACT HEADING ANGLE	. gigi	DEG.	117.99	DEG.	
REST T-FOSITION	84.56	FT.	22.90	FT.	
REST +-FOSITION	18.20	FI.	41.40	FŤ.	
REST HEADING ANGLE	16.50	DEG.	261.97	DEG.	
END-OF-ROTATION x-FUSITION	. 00	FI.	22,60	FT.	
END OF FOTATION & FUSITION	, whole	FT.	34,44	FT.	
END OF ROTATION HEADING ANGLE	. 66	D€G.	249.97	DEG.	
DIRECTION OF POTATION	CW		C₩		
AMOUNT OF ROTATION	366		360		

Figure 15 - CRASH3 with a point on curve which was on a straight line between impact and rest

No other significant differences relating to the calculations were identified.

Graphics

a Site Drawing (figure 19). The display was limited to the vehicle outlines shown in plan view and placed at the user-entered impact and rest positions. A vehicle was also displayed at the end of rotation if one was entered. If a point on curve was entered, it was displayed only as an x-y point, since a PSI (heading angle) value was not supplied, and the orientation of the vehicle was not established.

The vehicle dimensions were based on the user-entered size (class) categories. The scale of the accident site was established from the minima and maxima of the impact and rest positions.

Output data was also displayed. This output was limited to impact speeds, and positions at impact and rest.

Additional details, including titles, headings, and other results, were added by typing the desired information onto the display.

ENGINEERING DYNAMICS CORPORATION Date 12-09-1984 Time 12:17:44
RICSAC #7 CHEVELLE VS RABRIT

WARNING MESSAGES

Damage-based estimates for Magnitude of Principal Force grossly violate Newton's third law of motion. Review the output to determine required corrections to Damage Data and adjust is necessary. The Magnitudes of Principal Force for Vehicles 1 and 2 should be approximately equal.

User-entered point on curve for vehicle #1 was discarded because the position was practically on a straight line between impact and rest. If the post-impact path was curved and your point on curve was rejected the results may be erroneous. Check your data.

COMMON VELOCITY WARNING — An adjustment of vehicle separation conditions was performed in order to be consistent with the common velocity assumption. The adjustment does not exceed 10° percent.

```
| IMPACT SPEED (TRAJECTORY AND CONSERVATION OF LINEAR MOMENTUM)
| FORMARD | LATERAL | | | | |
| VEH | 81 | 25.9 | MFH | 0.8 | MFH |
| VEH | 82 | 24.7 | MFH | 0.8 | MFH |
| SPEED CHANGE (DAHAGE) |
| TOTAL | LONG. | LAT. | ANG. | | | | | | |
| VEH | 81 | 19.7 | MFH | -17.1 | MFH | 9.9 | MFH | -30.8 | DEG. |
| VEH | 82 | 43.8 | MFH | -17.1 | MFH | 9.5 | MFH | -30.8 | DEG. |
| SPEED CHANGE (LINEAR MOMENTUM) |
| TOTAL | LONG. | LAT. | ANG. | | | | | | |
| VEH | 81 | 14.8 | MFH | -13.2 | MFH | 6.5 | MFH | -28.1 | DEG. |
| VEH | 82 | 32.1 | MFH | -12.7 | MFH | 17.9 | MFH | 33.9 | DEG. |
| ENERGY DISSIPATED DY DAMAGE: | VEH | 81 | 23188.8 | FT-LB | VEH | 82 | 19.487.1 | FT-LB |
| ENERGY DISSIPATED DY DAMAGE: | VEH | 81 | 23188.8 | FT-LB | VEH | 82 | 19.487.1 | FT-LB |
```

RELATIVE VELOCITY DATA

	THE THRU CGS ILINEAR MOMENTUM
VEH #1	24.7 MEH
VEH #2	7.3 MFH
SPEED ORTHOG.	TO CO LINE (LINEAR MOMENTUM)
VEH #1	B. & MIII
VEH #2	-32.9 MEH

SCENE INFORMATION

	VEHICLE	• 1	VEHICLE	#2
IMPACT K-POSITION	8.00	Ft.	10.70	FT.
IMPACT V FOSITION	3.00	FT.	3.45	FT.
IMFACT HEADING ANGLE	8.00	DEG.	119.99	D€G.
REST X FOSTION	84.50		22.90	FT.
REST Y FOSITION				
	13.10		41.40	
REST HEADING ANGLE	15.50	DEG.	261.97	DEG.
END-OF-ROTATION X-POSITION	1.00	FI.	22.00	FT.
END OF ROTATION + FOSITION	4. 184	FT.	70.00	FT.
END OF ROTATION HEADING MINULE	2. 424.5	DEG.	249.97	DEG.
DIRECTION OF POTATION	CM		CW	
AMOUNT OF ROTATION	3641		366	

Figure 16 - EDCRASH with a point on curve which was on a straight line between impact and rest

CONCLUSIONS

- 1. The CRASH program, either EDCRASH or CRASH3, represented an effective means of reconstruction for most single- and two-vehicle accidents.
- 2. EDCRASH and CRASH3 required the same input data.
- 3. EDCRASH produced additional output when compared to CRASH3, including the Magnitude of Principal Force and Graphics.
- 4. The major difference between EDCRASH and CRASH3 was user-interactivity. This was the result of substantial differences in program design.

WARNING* SEPARATION VELOCITIES ALONG DOPF ARE
NOT COMPATIBLE, ACCORDING TO ASSUMPTION OF A
COMMUN VELOCITY AT THE DAMAGE AREA CENTROIDS.

RICSAC #7 CHEVELLE VS RABBIT

SUMMARY OF RESULTS

[M	PACT SPEED	(TRAJECTORY AN	ID CONSERVATION	ON OF LINEAR 1	10MENTUM)
	FORWARD	LATERAL			
VEH#1	35.7 MEH	.e MPH			
VEH#2	45.9 MPH	.a MPH			
SF	EED CHANGE	(DAMAGE)			
	TOTAL	LONG.	LAT.	ANG.	
VEH#1	19.7 MFH	-17.1 MPH	9.9 MFH	-30.0 DEG.	
VEH#2	43.0 MEH	-37.2 MFH	-21.5 MPH	30.0 DEG.	
SF.	EED CHANGE	ILINEAR MOMENT	'UM)		
	TOTAL	LONG.	LAT.	ANG.	
VEHEL	18.8 MEH	15.8 MFH	10.2 MFH	-32.9 DEG.	
		36.4 MPH			
ENERG:	DISSUATED	D En DAMAGE ME	H#1 27188.8	FT-LB VEH#2	196486.9 FT LE

RELATIVE VELOCITY DATA

SEEED ALONG	LINE THRU COS	LINEAR MOMENTUM
∨EH#1	33.9 MEH	
VEH#1	9.2 MPH	
SPEED OF THOG	. TO CG LINE	(LINEAR MOMENITUM)
₩ €++#1	10.7 MEH	
VEH#2	42.9 MPH	
CHUSING VELO	CITY (LINEAR	MOMENTUM)
	40.1 MEH	

SCENE INFORMATION

Jeene				
	VEHICLE .	1	VEHICLE *	2
IMPACT x POSITION IMPACT x POSITION	.00	FT. FT. DE3.	10.70 3.45 119.99	FT.
IMPACT HEADING ANGLE	. 8/8/	DC 3.		•
FEST & PUSITION FEST & FUSITION FEST HEADING ANGLE	84.50 18.70 16.50	FT.	22.90 41.40 261.97	FT.
END-OF-ROTATION X POSITION END OF FOLKATION : POSITION END OF FOLKATION DEBUTION WHOLE	244	FT. FT. UEU.	22.00 30.00 14.93	
FOINT ON CORVE F-FOSITION	40.00 85.00			
STRECTION OF ROTATION SHOUNT OF ROTATION	. 294 CM		. 29€ 139€	

Figure 17 - CRASH3 with errant point on curve

- 5. A difference in processing time was identified. The difference was not significant unless a trajectory simulation was requested, wherein a CDC-Cyber mainframe (CRASH3) required 4.5 seconds compared to about 5 minutes for EDCRASH. Without a trajectory simulation, CRASH3 required approximately 1 second while EDCRASH required about 5 seconds.
- 6. EDCRASH and CRASH3 produced different results when the post-impact path for vehicle #2 had an end of rotation. This was the result cf an error found in CRASH3.
- 7. EDCRASH and CRASH3 usually produced slightly different results when a trajectory simulation was requested. This was primarily the result of the end-of-rotation error (above).
- 8. EDCRASH and CRASH3 handled the case of a post-impact point on curve differently. EDCRASH performed an additional validity check to help insure valid data and corresponding results.
- 9. EDCRASH generated additional warning messages, both informative and fatal, resulting from validity checks for damage data and common

SUMMARY OF EDCRASH RESULTS

ENGINEERING DYNAMICS CORPORATION Date 12:09-1984 Time 12:20:05
RICSAC #7 CHEVELLE US RAIBIT

WARNING MESSAGES:

Damade based estimates for Magnitude of Principal Force grossly violate Newton's third law of motion. Reliew the output to determine required corrections to Damage Date and adjust as incressory. The Magnitudes of Principal Force for Vehicles I and 2 should be approximately equal.

Usermentered point on curve for vehicle %1 was discarded because the position was too far away from other path coordinates to make sense. If the post-impact path was curved and your point on curve was rejected the results may be erromeous. Check your data.

COMMON VELOCITY WARNING \cdots an adjustment of vehicle separation conditions was performed in order to be consistent with the common velocity assumption. The adjustment does not exceed \mathbb{R}^d percent,

PELATIVE VELOCITY DATA

SFEED ALONG L	INE THEU LO	(LINEAR MUMENTUM)
VEH #1	.4. MEH	
VEH #2	7.3 MPH	
SPEED OF THOO.	TO CO LINE	(LINEAR MOMENTUM)
VEH #1	8.0 MF11	
VEH #2	33.9 HEH	
CLUSING VELOC		MONENTUM)
	51.9 MEH	

SCENE INFORMATION

	WEHICLE	•1	VEHICLE	•2
IMPACT X-POSITION	0.00	FT.	10.70	FT.
IMPACT + FUSITION	4.00	FT.	3.45	FT.
IMPACT HEADING ANGLE	0.00	D€G.	119.99	DEG.
HEST C FOSTION	94.5	+ T .	22.98	FT.
REST (-FOSTITION	18. 2v		41.40	
REST HEADING ANGLE	15.54		261.97	
END-OF ROTATION x FUSITION	9.00	e t	22.00	FT.
END OF ROTATION (POSITION	e1, ph		74.00	FT.
		DEG.	249.97	DEG.
END OF-ROTATION HEADING ANGLE		DEG.		DEG.
DIFECTION OF ROTATION	CM		C₩	
AMOUNT OF ROTATION	Jou'			

Figure 18 - EDCRASH with errant point on curve

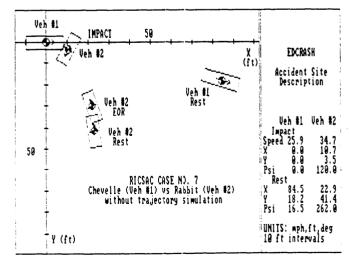


Figure 19 - EDCRASH Site Drawing

velocity to insure valid data and corresponding results.

10. EDCRASH produced a graphics display of the results.

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